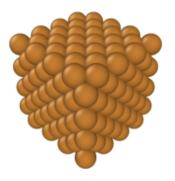


Symmetry-Preserving Neural Networks

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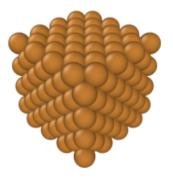




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Physical Symmetries

• Translation $E = E(x_1 + \Delta x, x_2 + \Delta x, \dots, x_n + \Delta x)$

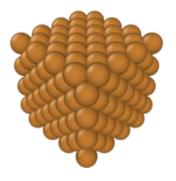




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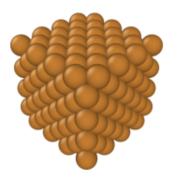
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• Rotation
$$E = E(Rx_1, Rx_2, \dots, Rx_n)$$

• Permutation
$$E = E(\boldsymbol{x}_{\sigma(1)}, \boldsymbol{x}_{\sigma(2)}, \cdots, \boldsymbol{x}_{\sigma(n)})$$





Example Problem 2: Transport Equation

$$\Delta c(\mathbf{x}) - \nabla \cdot (\mathbf{u}(\mathbf{x})c(\mathbf{x})) + S(c(\mathbf{x})) = 0$$



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Spatial discretization: $x_1, x_2, \dots, x_n, u_1 = u(x_1), u_2 = u(x_2), \dots, u_n = u(x_n),$

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$$I:=\int_{\Omega}c(x)\mathrm{d}x\approx I(x_1,x_2,\cdots,x_n,u_1,u_2,\cdots,u_n)$$



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Problem Setup

A function f maps a set of coordinates to a scalar output

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Why symmetry-preserving?

- respect the physics
- better data efficiency
- better accuracy



• Handcrafted features, kernel method: Gaussian Approximation Potentials (GAP), Smooth Overlap of Atomic Positions (SOAP), etc.



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- Group representation: Group Equivariant Convolutional Networks, Steerable Convolutional Neural Networks, Clebsch–Gordan Nets, etc.



Translation and Rotation Symmetry

Translation: always use relative coordinates

$$(x_1, x_2, \dots, x_n) \mapsto (x'_1, x'_2, \dots, x'_n) = (x_1 - \bar{x}, x_2 - \bar{x}, \dots, x_n - \bar{x})$$



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$$D'_{ij} = \mathbf{x}'_i \cdot \mathbf{x}'_j$$
 or $D' = X^T X$ with $X = [\mathbf{x}'_1, \mathbf{x}'_2, \cdots, \mathbf{x}'_n]^T$



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However, it lacks permutational invariance



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Deep Sets: a function f operating on a set $\{x_i\}_{i=1}^n$ can be represented by

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$$z_1^2 + z_2^2 + z_1 z_2 = \frac{1}{2}(z_1 + z_2)^2 + \frac{1}{2}(z_1^2 + z_2^2)$$

Let
$$\phi(z) = [z, z^2]^{\mathsf{T}}$$
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Ansatz: parameterize ϕ , ρ with neural networks



Introduce a set of m embedding functions $\{\phi_k(\,\cdot\,)\}_{k=1}^m$

$$L_{kj} = \frac{1}{n} \sum_{i=1}^{n} \phi_k(|x_i'|) x_{ij}', \quad k = 1, \dots, m, j = 1, 2, 3$$

or
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Guarantee equivariance if the output is

$$\text{vector: } \boldsymbol{r} = f(\boldsymbol{x}_1, \boldsymbol{x}_2, \cdots, \boldsymbol{x}_n) \quad \rightarrow \quad R\boldsymbol{r} = f(R\boldsymbol{x}_1, R\boldsymbol{x}_2, \cdots, R\boldsymbol{x}_n) \\ \text{or tensorr: } \boldsymbol{Q} = f(\boldsymbol{x}_1, \boldsymbol{x}_2, \cdots, \boldsymbol{x}_n) \quad \rightarrow \quad R\boldsymbol{Q}\boldsymbol{R}^\top = f(R\boldsymbol{x}_1, R\boldsymbol{x}_2, \cdots, R\boldsymbol{x}_n)$$



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- Guarantee invariance and equivariance if we have additional scalar/vector/ tensor features attached to each point
- Use high-order information to do embedding



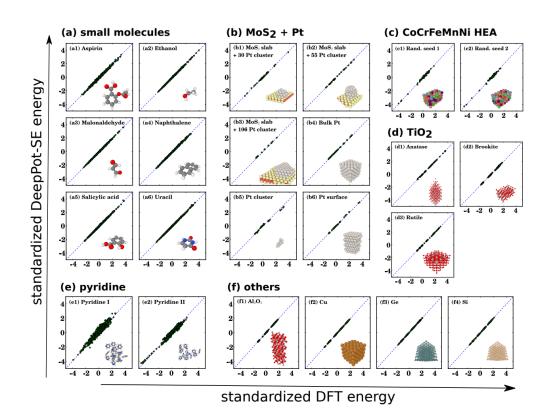
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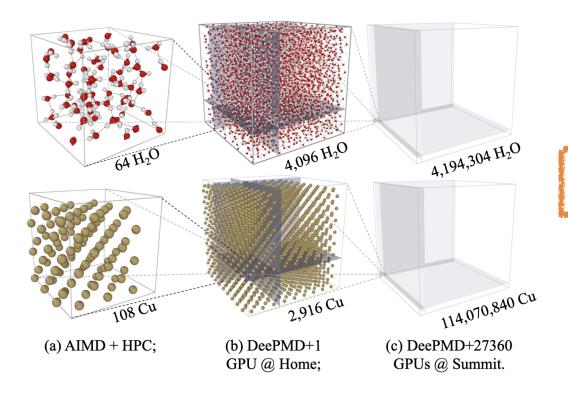
Open question: universal approximation property with practical optimality and scalability

Application: Molecular Dynamics





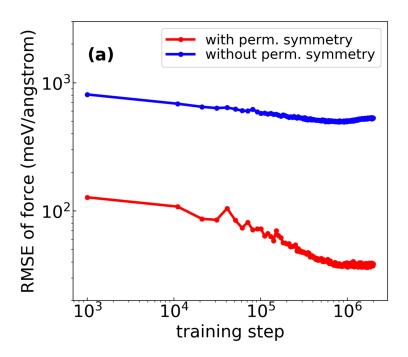
Application: Molecular Dynamics



n is bounded as system size increased by short-range effect

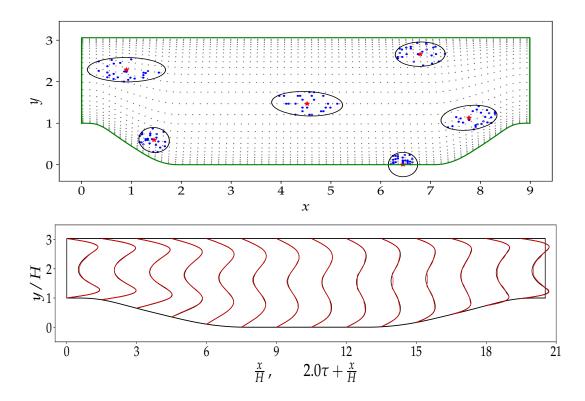


Importance of Symmetry





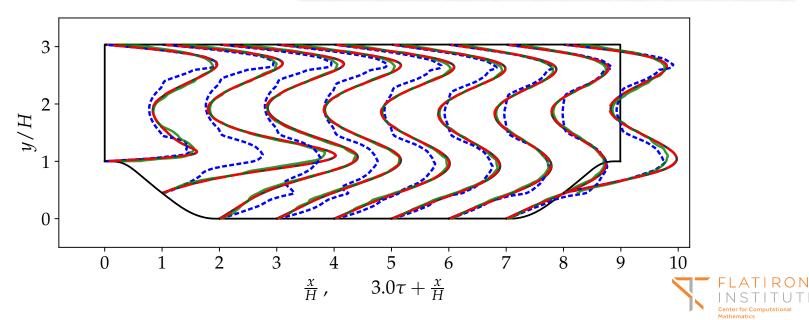
Application: Transport Equation





Adaptivity to Different Sizes

ground truth ---- local (n = 1) coarse nonlocal (n = 25) -- baseline nonlocal (n = 150)



References

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- W. Jia, H; Wang, M. Chen, D. Lu, J. Liu, L. Lin, R. Car, W. E, L. Zhang, *Pushing the limit of molecular dynamics with ab initio accuracy to 100 million atoms with machine learning*, 2020.
- X.-H. Zhou, J. Han, and H. Xiao, Frame-independent vector-cloud neural network for nonlocal constitutive modelling on arbitrary grids, arXiv:2103.06685, accepted by CMAME.

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